

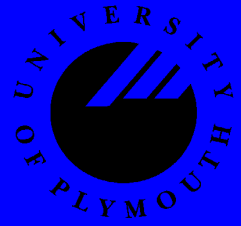
Absorbing Re-reflected Random Waves in SPH

David Graham, Jason Hughes,
John Lawrence

Phil James, Dominic Reeve,
Andrew Chadwick

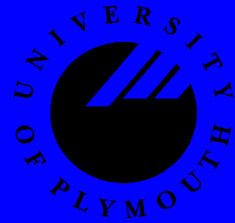
C-CODE,
University of Plymouth
UK

SPHERIC workshop
Rome May 10-12 2006



Outline

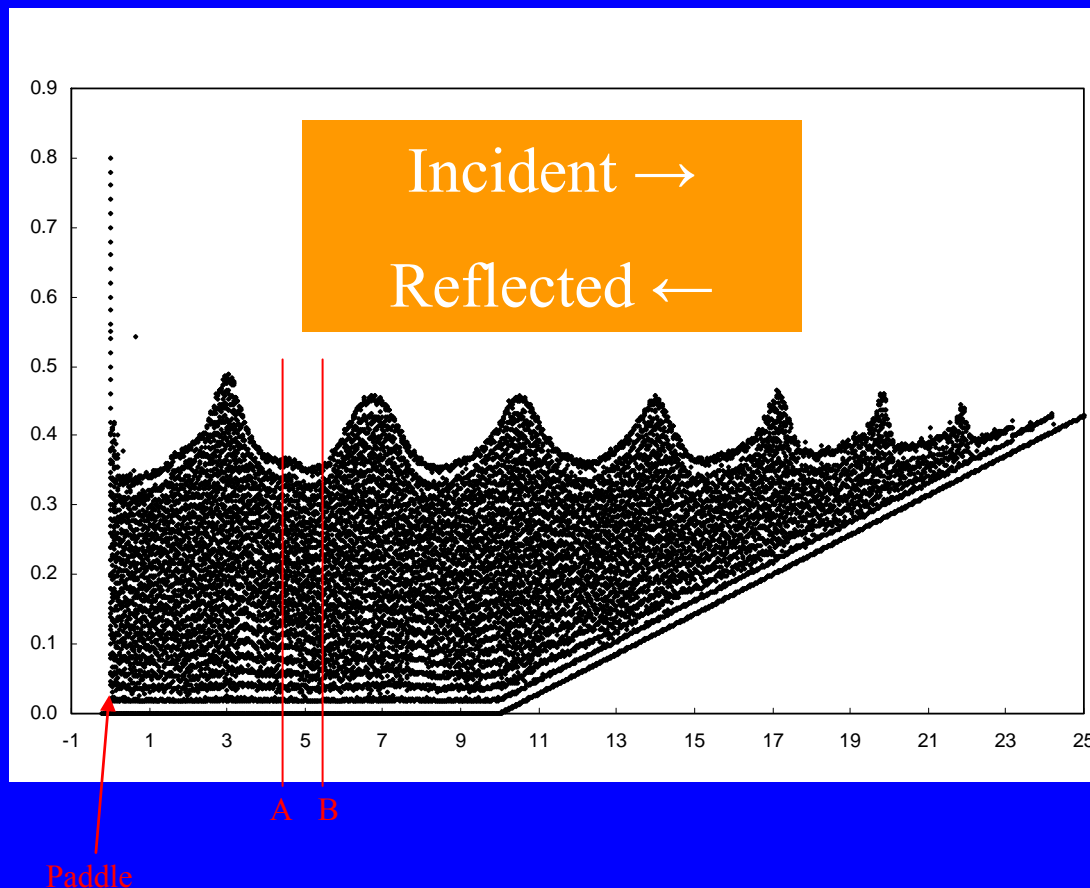
- **Motivation**
- **Re-reflection from Wave paddle**
 - Frigaard & Brorsen model
- **Implementation in SPH**
- **Conclusions and Further Work**



Motivation

- *Wave overtopping*
 - structures can be highly reflective
 - limited info from regular waves
- *Physical / numerical modelling*
 - need random waves
 - reflected waves re-reflected by paddle
 - can spoil statistics of random wave train
- *Preventing re-reflection*
 - need to know about reflected waves at paddle
 - method of Frigaard & Brorsen
- *How does method work in SPH?*
 - Noisy data
 - need to 'clean' data
 - What are issues?

Frigaard-Brorsen Method



- *Outline of method*

- *Paddle at x_0*
- *Measurements at A (x_1), B (x_2)*

$$\eta(x,t) = \eta_I(x,t) + \eta_R(x,t)$$

$$= a_I \cos(2\pi ft - kx + \Phi_I) + a_R \cos(2\pi ft + kx + \Phi_R)$$



Frigaard-Brorsen Method

$$\eta^*(x_n, t)$$

$$= Ca_L \cos(2\pi ft - kx_n + \Phi_L + \Phi_n^{th}) \\ + Ca_R \cos(2\pi ft + kx_n + \Phi_R + \Phi_n^{th})$$

$$\eta^{calc}(t) = \eta^*(x_1, t) + \eta^*(x_2, t)$$

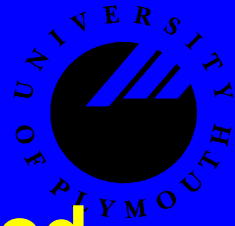
$$\eta^{calc}(t) = \eta_R(x_0, t) \quad \text{when}$$

$$\Phi_2^{th} = -k(x_1 - x_0) + \pi/2$$

$$\Phi_1^{th} = -k(x_2 - x_0) - \pi/2$$

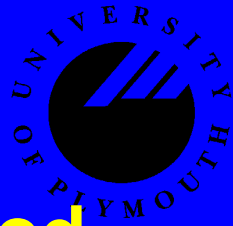
$$C = 1/[2 \cos(-k(x_2 - x_1) - \pi/2)]$$

- *In frequency space, amplify and phase shift signals from measurement stations 1, 2 then combine together*



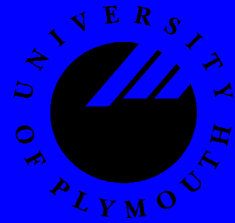
Frigaard-Brorsen Method

- *Process (conceptual)*
 - *Take (Discrete) Fourier transform of signals*
 - Y_1, Y_2
 - *Multiply by digital filters with impulse responses H_1, H_2 to amplify and phase-shift signals*
 - $H_1 Y_1, H_2 Y_2$
 - *combine together*
 - $H_1 Y_1 + H_2 Y_2$
 - *Inverse (Discrete) Fourier transform gives required signal*
 - *inverse of product of DFT's is discrete convolution*



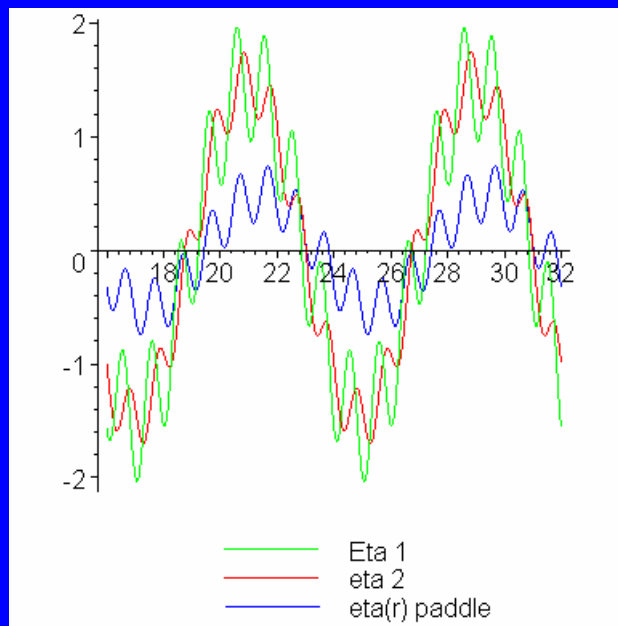
Frigaard-Brorsen Method

- *Process (in practice):*
 - *Find inverse (Discrete) Fourier transform of H_1, H_2 giving h_1, h_2*
 - *find discrete convolution of η_1 with h_1, η_2 with h_2 and add together to give reflected wave at paddle*
- **MAPLE code**
 - **for j from 1 to N do:**
 - **if (j <= NA) then:**
 - **pj:= p-j+1:**
 - **else:**
 - **pj:= p-j + N/2 +1:**
 - **end if:**
 - **end if:**
 - **deta:=h1[j]*eta1[pj]+h2[j]*eta2[pj]:**
 - **eta[p]:=eta[p]+deta:**
 - **end do:**

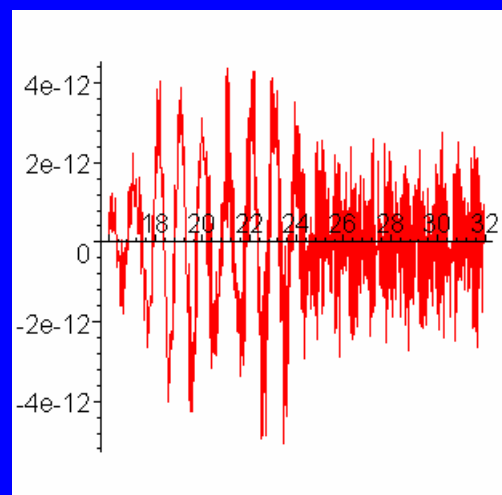


Algorithm test 1

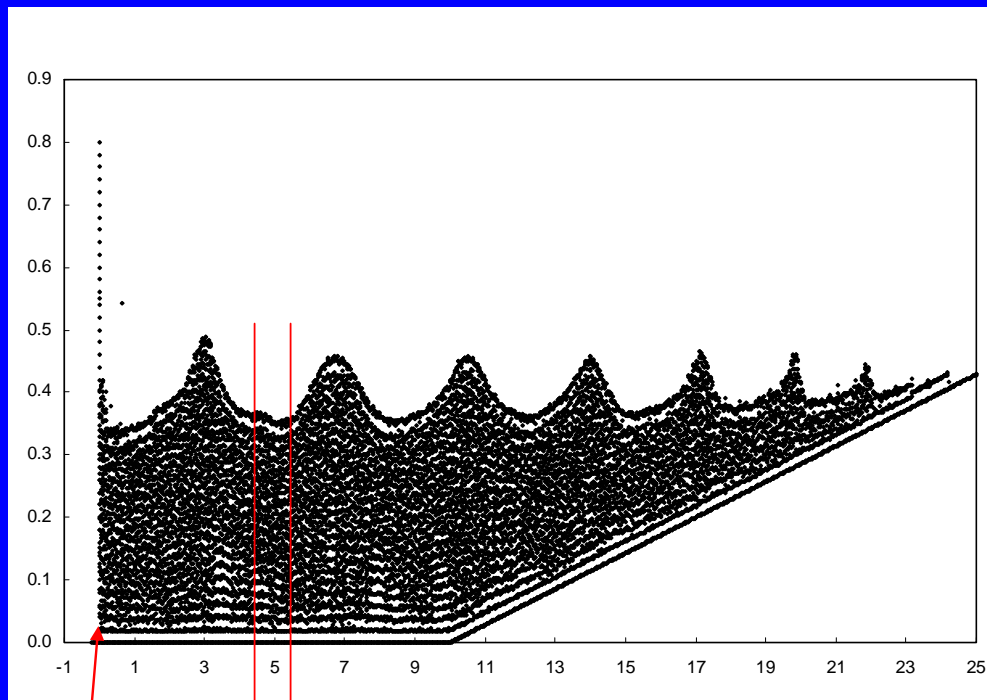
$f1 = df$; $f2 = 8df$



Method is essentially exactly when frequency is integer multiple of df



Implementation in SPH



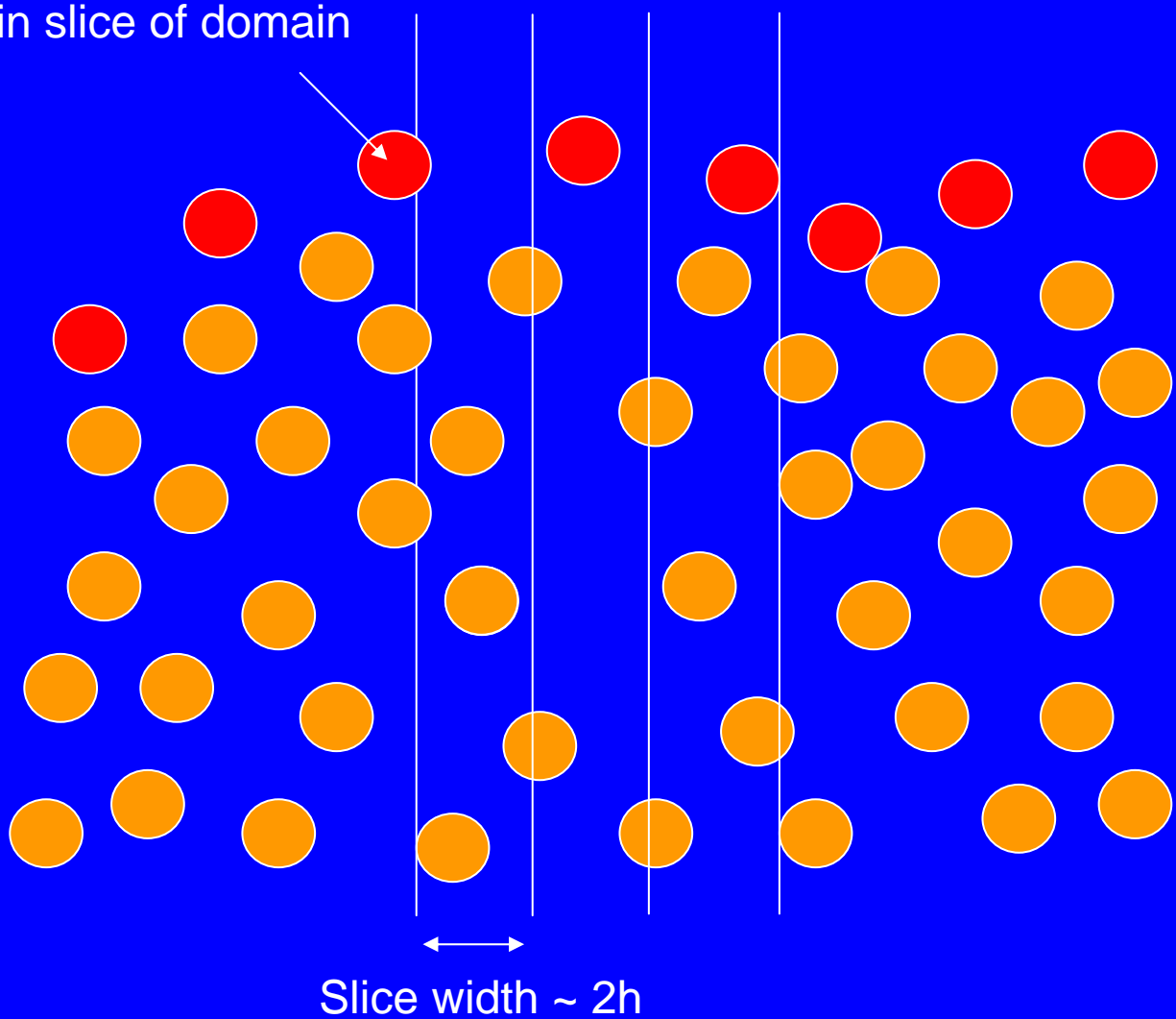
Paddle

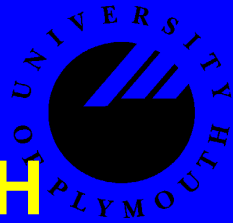
- *I-SPH: Songdong Shao*
- *Details*
 - $dt = 2^{(-10)} \sim .001s$
 - *Depth 0.4m*
 - *Period 2s*
 - *Amplitude $\sim 0.1m$*
 - *18,800 particles*

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Surface elevation in SPH

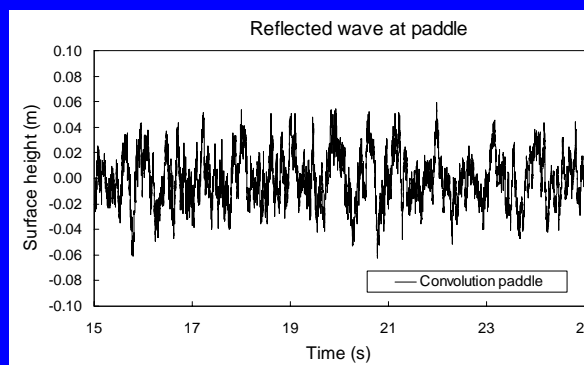
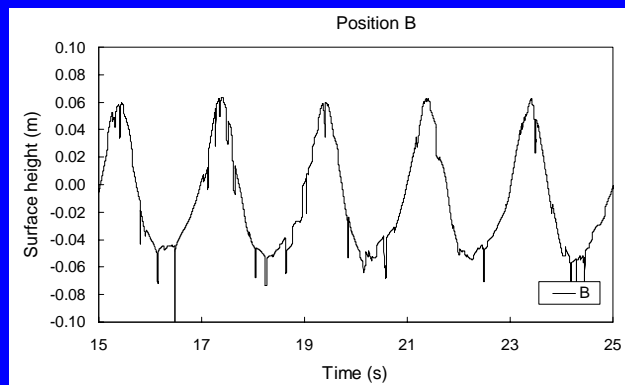
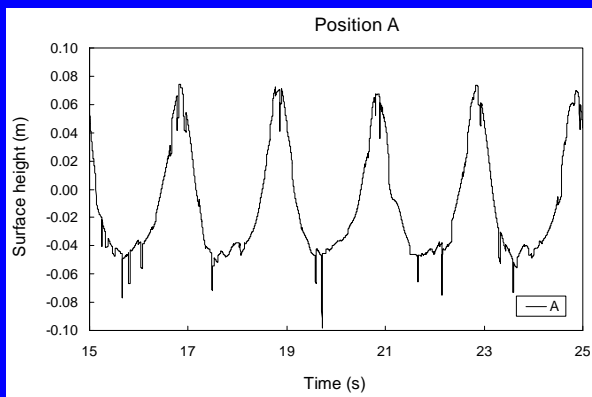
Free surface: highest point in slice of domain





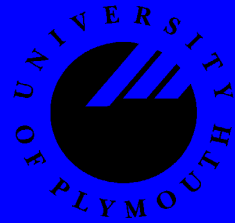
Implementation in SPH

$df = .25; f = .5$



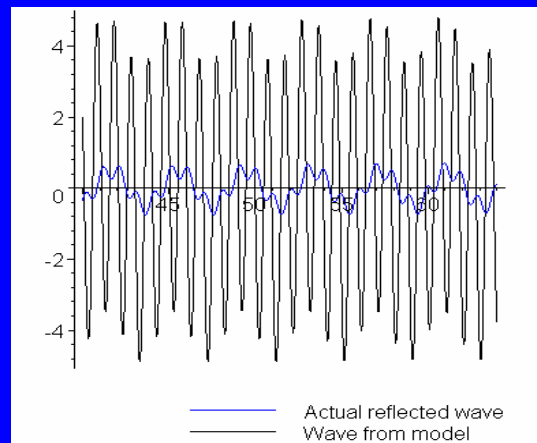
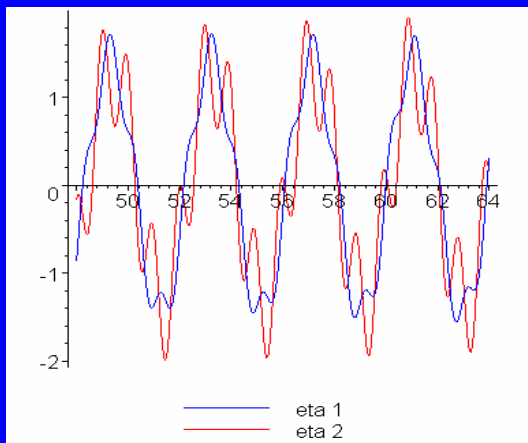
Noisy SPH data produce noisy output even when frequency is exact multiple of df !

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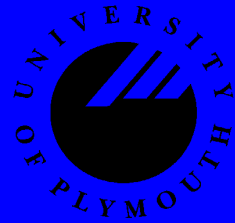


Algorithm test 2

$f1 = 2.05df$; $f2 = 8.1df$

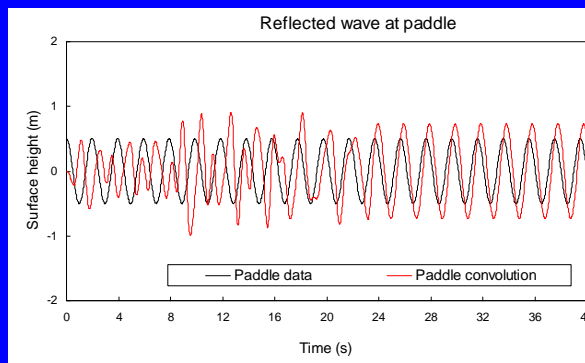


F-B Method performance degenerates when frequency is non-integer multiple of df .

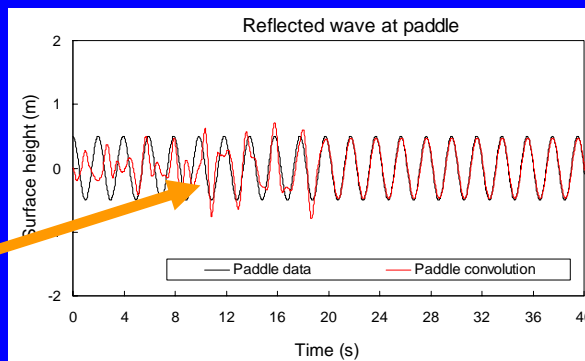


Algorithm test 3

$f1 = 4.05df$

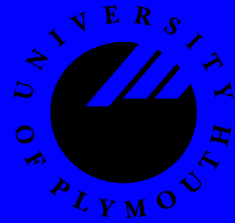


Filter needs
to 'warm
up'

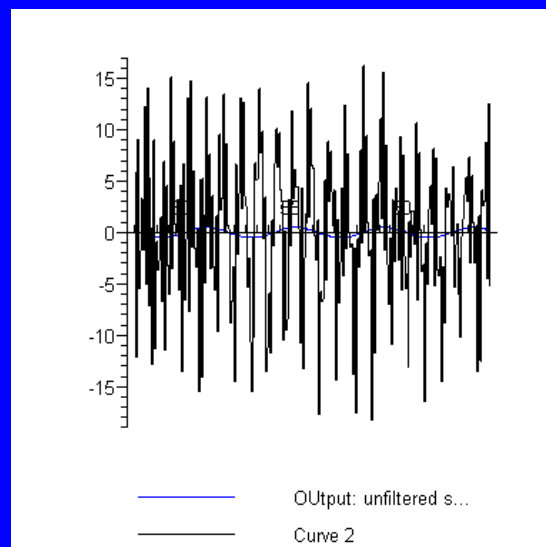
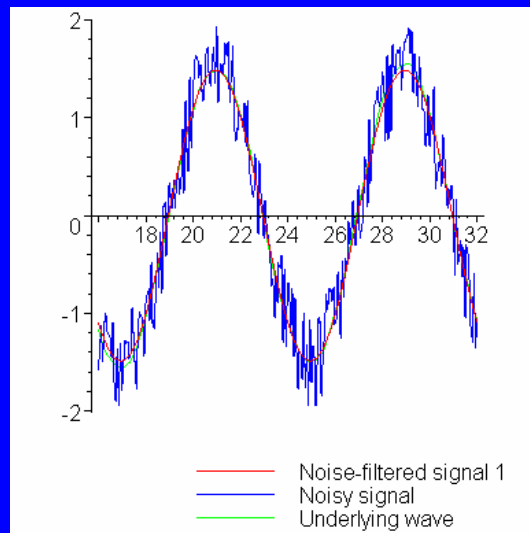


'Circular' convolution (bottom figure) can improve performance but not available in real-time simulations

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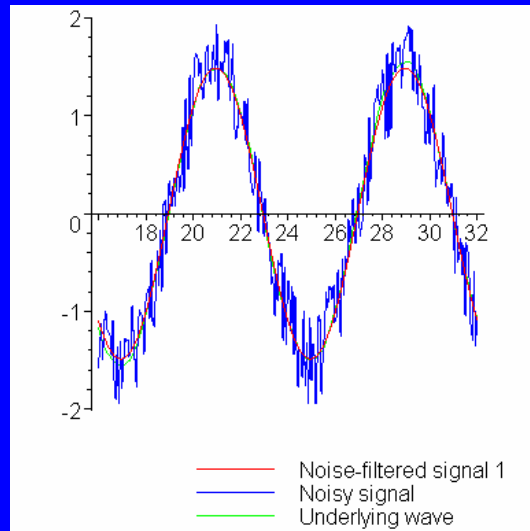
Algorithm test 4 Random noise



Frigaard-Brosen does not work if 'noise' is random

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Noise filtering

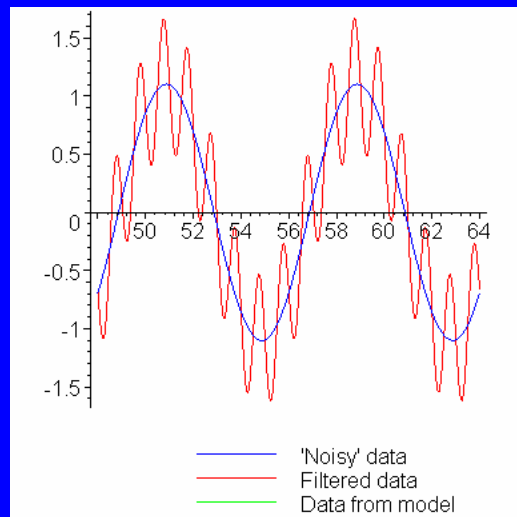


- *Theory:*
 - *Signal consists of high-frequency 'noise' over desired low-frequency signal*

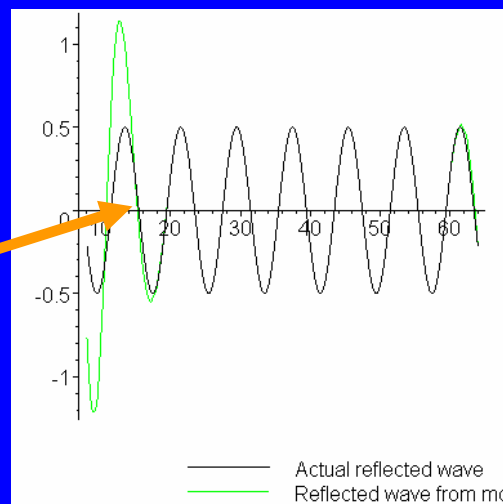
- *Process:*
 - *Define low-pass digital filter f*
 - *frequency increment df*
 - *Cutoff frequency $n_{max} * df$*
 - *find discrete convolution of η_1, η_2 with f to give 'cleaned signal'*

Noise filtering test 1

$f_1 = df$; $f_2 = 8df$; cutoff $4df$



Filter needs to 'warm up'

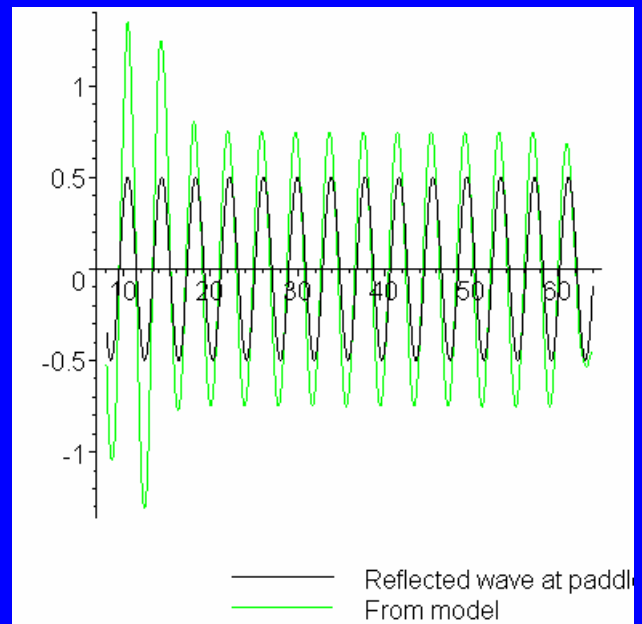
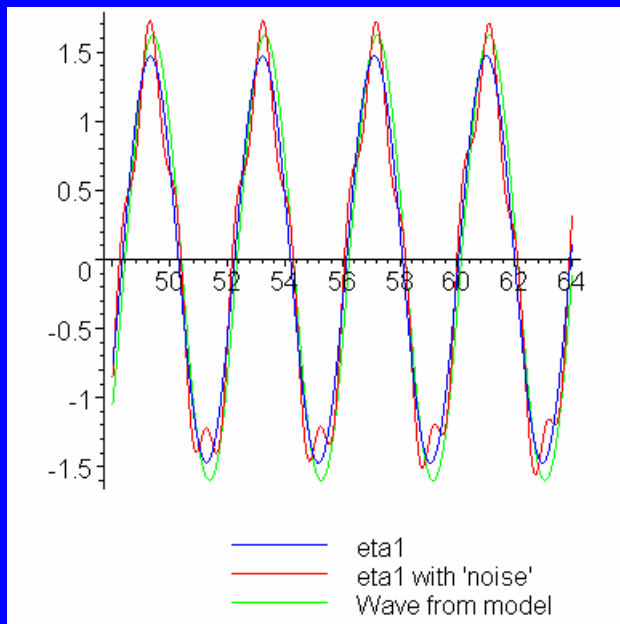


Noise filtering works in conjunction with Frigaard-Brorsen method if 'noise' is high-frequency sinusoid.



Noise filtering test 2

$f_1=2.01df$; $f_2=8.1df$; cutoff $4df$

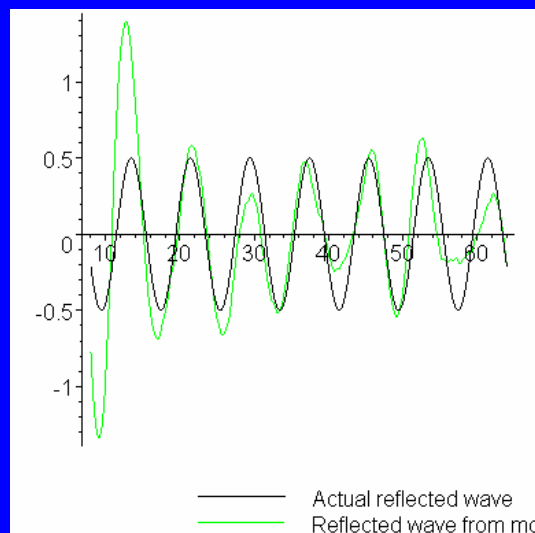
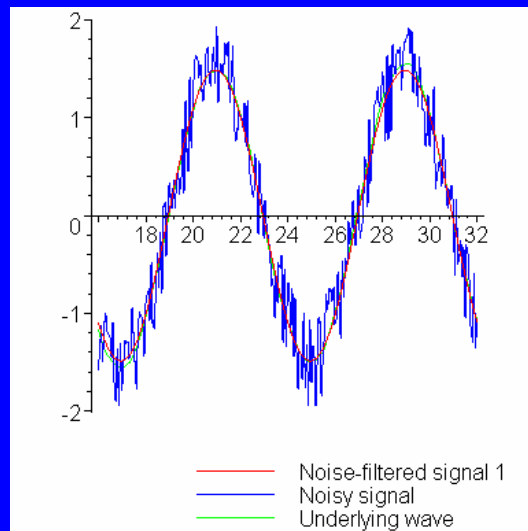


Noise filtering with Frigaard-Brorsen performance affected if frequencies aren't integer multiples of df

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Noise filtering test 3

Random noise

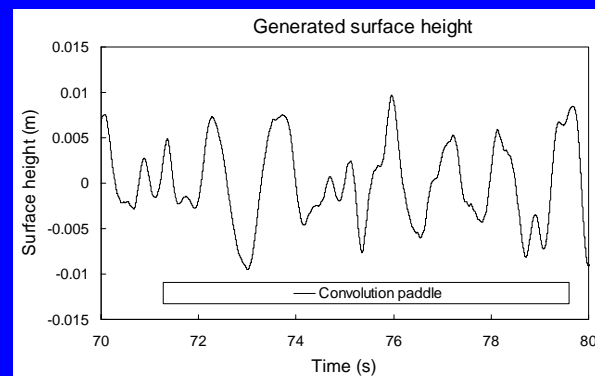
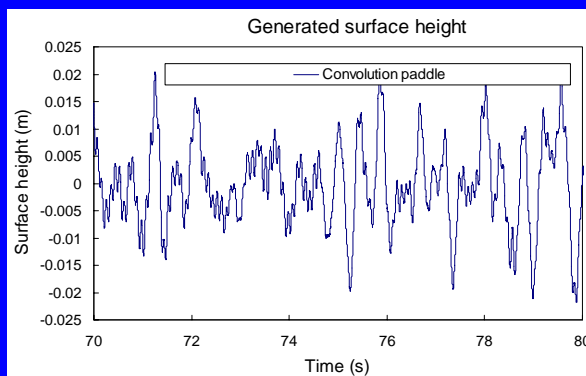
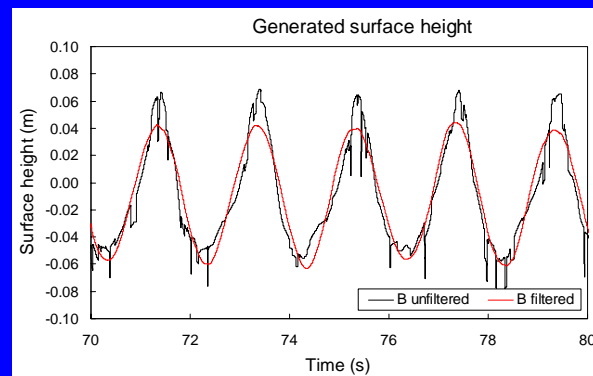
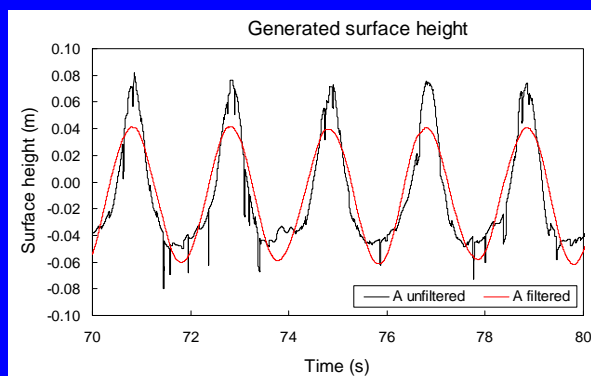


Noise filtering with F-B works if 'noise' is random (but only with 'circular convolution' and then not as well as if noise is periodic)



Implementation in SPH

$df = .25$; Wave $f = .5, f < 1.25, 10^{12}$
modes noise filter / convolution



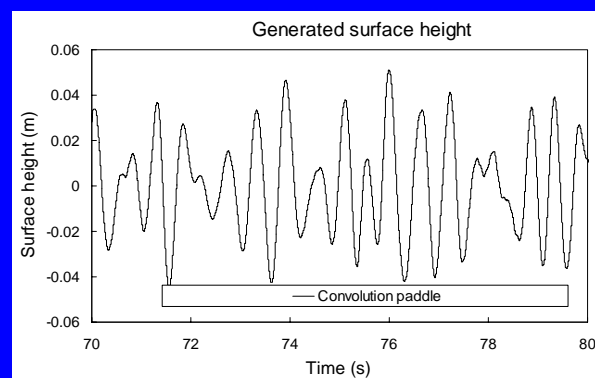
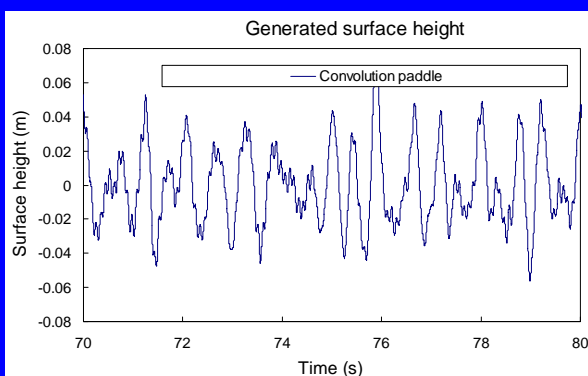
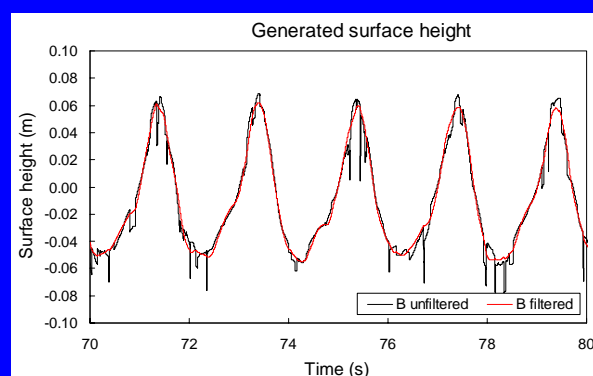
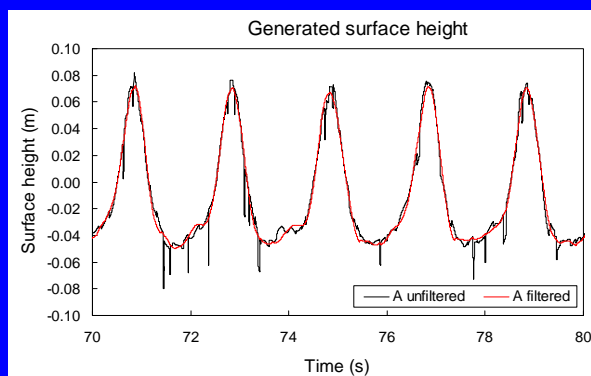
Noise reduction 'cleans' SPH elevation signal: apparently effective

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Implementation in SPH

$df = .25$; Wave $f = .5, f < 2.25, 10^{12}$
modes noise filter / convolution



But increasing resolution of wave increases
computed magnitude of reflected wave????

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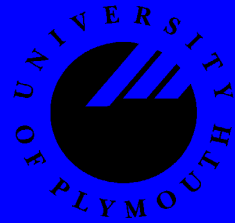
Development for Random Waves

- **F-B method**
 - Works with any combination of waves with frequency $i \cdot df$
- **Spectrum**
 - Discrete approximation to given spectrum
 - Pseudo-random (actually periodic)
 - Components at integer multiples of df from noise filter / anti-reflection convolution
- **Implementation in SPH**
 - No further complications envisaged in addition to those from
 - Warm-up times for filters
 - Noisy data
 - Drift of frequencies from $i \cdot df$



Conclusions and Further Work

- **Anti-reflection**
 - Frigaard-Brorsen method works with ideal examples
 - Deteriorates when frequencies depart from ideal
 - Works poorly with signals with random noise
 - 'circular convolution' can improve results but requires data from future
- **Implementation in SPH**
 - Noisy signals cause problems
 - Departure from desired frequency
 - 'circular convolution' not available for real-time SPH
- **Future**
 - Combine anti-reflection / noise reduction?
 - Better method to define surface height?
 - Translate reflected wave height to paddle motion
 - moving paddle



References

- **Peter Frigaard & Michael Brorsen (1995):** A time-domain method for separating incident and reflected irregular waves. *Coastal Eng* 24, 205-215.
- **Songdong Shao and Edmond Y. M. Lo (2003):** Incompressible SPH method for simulating Newtonian and non-Newtonian flows with a free surface. *Journal of Advances in Water Resources*, V 26 no. 7 pp 787-800,.